

# ID3

## ARX Identification



### 3.19 BIAS AND CONSISTENCY OF MULTIVARIABLE LS ESTIMATES

To evaluate the properties of least squares estimates (3.18.4) we will start from the expression

$$y_i^\circ = H_i \theta_i^* + e_i^\circ \quad (3.19.1)$$

where  $\theta_i^*$  denotes the vector of true parameters of the  $i$ -th subsystem of model (3.17.2). Following the same procedure already considered in Module 3.5 we obtain, from (3.18.4) and (3.19.1)

$$\begin{aligned} \text{plim}_{N \rightarrow \infty} \theta_i^\circ &= \text{plim}_{N \rightarrow \infty} \left[ (H_i^T H_i)^{-1} H_i^T (H_i \theta_i^* + e_i^\circ) \right] \\ &= \theta_i^* + \text{plim}_{N \rightarrow \infty} \left[ (H_i^T H_i)^{-1} H_i^T e_i^\circ \right] \\ &= \theta_i^* + \text{plim}_{N \rightarrow \infty} \left[ \left( \frac{H_i^T H_i}{N} \right)^{-1} \frac{H_i^T e_i^\circ}{N} \right] \\ &= \theta_i^* + \text{plim}_{N \rightarrow \infty} \left[ \left( \frac{H_i^T H_i}{N} \right)^{-1} \right] \text{plim}_{N \rightarrow \infty} \left[ \frac{H_i^T e_i^\circ}{N} \right]. \end{aligned} \quad (3.19.2)$$

Because of structure (3.18.1) of  $H_i$ , the product  $H_i^T e_i^\circ$  has components given by the following terms

$$H_{v_{i1}}^T (y_1) e_i^\circ, \dots, H_{v_{im}}^T (y_m) e_i^\circ, H_{v_i}^T (u_1) e_i^\circ, \dots, H_{v_i}^T (u_r) e_i^\circ. \quad (3.19.3)$$

It is now easy to verify that the  $k$ -th element of  $H_{v_{ij}}^T (y_j) e_i^\circ / N$  is given, for  $i \neq j$ , by

$$\left[ \frac{H_{v_{ij}}^T (y_j) e_i^\circ}{N} \right]_k = \frac{1}{N} \sum_{s=0}^{N-1} y_j(k+s) e_i(v_i+s+1) \quad (k = 1, \dots, v_{ij}) \quad (3.19.4)$$

and that

$$\text{plim}_{N \rightarrow \infty} \frac{1}{N} \sum_{s=0}^{N-1} y_j(k+s) e_i(v_i+s+1) = 0 \quad (k = 1, \dots, v_{ij}) \quad (3.19.5)$$

because of the independence of the errors  $e_j(t)$  present on  $y_j$  from  $e_i(t)$ . For  $i = j$  we obtain

$$\left[ \frac{H_{v_i}^T(y_i) e_i^\circ}{N} \right]_k = \frac{1}{N} \sum_{s=0}^{N-1} y_i(k+s) e_i(v_i+s+1) \quad (k = 1, \dots, v_i) \quad (3.19.6)$$

and

$$\text{plim}_{N \rightarrow \infty} \frac{1}{N} \sum_{s=0}^{N-1} y_i(k+s) e_i(v_i+s+1) = 0 \quad (k = 1, \dots, v_i) \quad (3.19.7)$$

because of the whiteness of  $e_i(t)$  and of the difference between the indexes of  $y_i$  and  $e_i$  in (3.19.7), always greater or equal to 1. Finally

$$\left[ \frac{H_{v_i}^T(u_j) e_i^\circ}{N} \right]_k = \frac{1}{N} \sum_{s=0}^{N-1} u_j(k+s) e_i(v_i+s+1) \quad (k = 1, \dots, v_i) \quad (3.19.8)$$

and

$$\text{plim}_{N \rightarrow \infty} \frac{1}{N} \sum_{s=0}^{N-1} u_j(k+s) e_i(v_i+s+1) = 0 \quad (k = 1, \dots, v_i) \quad (3.19.9)$$

because of the independence between input sequences and equation errors. It follows that

$$\text{plim}_{N \rightarrow \infty} \theta_i^\circ = \theta_i^* \quad (3.19.10)$$

i.e. that the LS estimate of the multivariable ARX model (3.17.6) is unbiased.

**Remark 3.19.1** – The whiteness of the components of  $e(t)$  allows to establish, like in the scalar case, that

$$\lim_{N \rightarrow \infty} \left[ \frac{H_i^T e_i^\circ}{N} \right] = 0 \quad (3.19.11)$$

with probability 1, i.e. that the obtained estimate is consistent.

**Remark 3.19.2** – Note that the independence between the components of  $e(t)$  plays an essential role in establishing the unbiasedness of multivariable LS estimates because in relation (3.19.4)  $v_{ij}$  can be equal to  $v_i + 1$ . In this case (3.19.4) includes synchronous products  $e_i(t)e_j(t)$  that allow to establish (3.19.6) only when  $e_i(t)$  and  $e_j(t)$  are independent.

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