

ID5

MA

Identification



5.1 MA MODELS

MA (Moving Average) models describe processes whose output is a moving average of samples of a white process. In the scalar case these models are described by relation

$$y(t) = w(t) + \gamma_n w(t-1) + \dots + \gamma_1 w(t-n) \quad (5.1.1)$$

where $w(\cdot)$ denotes a stochastic white process with null expected value, $E[w(t)] = 0$, and n is the order of the process. Introducing the polynomial in z^{-1}

$$r(z^{-1}) = 1 + \gamma_n z^{-1} + \dots + \gamma_1 z^{-n}, \quad (5.1.2)$$

model (5.1.1) can be written in the compact form

$$y(t) = r(z^{-1}) w(t). \quad (5.1.3)$$

Making reference to forward notations, (5.1.1), (5.1.2) and (5.1.3) become

$$y(t+n) = w(t+n) + \gamma_n w(t+n-1) + \dots + \gamma_1 w(t) \quad (5.1.4)$$

$$r(z) = z^n + \gamma_n z^{n-1} + \dots + \gamma_1 \quad (5.1.5)$$

$$z^n y(t) = r(z) w(t). \quad (5.1.6)$$

Model (5.1.6) can be written in the form

$$y(t) = \frac{r(z)}{z^n} w(t) = F(z) w(t) \quad (5.1.7)$$

which evidences how MA processes, like AR ones, can be considered as generated by a filter driven by a remote white process (Figure 5.1.1).

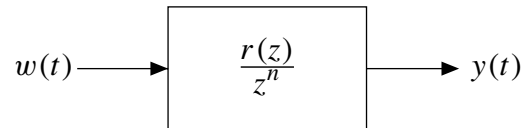


Figure 5.1.1 - Structure of a MA process

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