



Fault Diagnosis, Fault-tolerant Control, and Cooperative Control of Manned and Unmanned Aircraft Systems

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Outline of the Tutorial

- 1.08:30 09:05 Introduction to Fault-tolerant Control and Cooperative Control: Motivation, Concept, History, Existing and Future Developments (Dr. Zhang)
- 2.09:05 09:40 Developments on Fault Diagnosis, Fault-tolerant Control and Cooperative Control with Applications to Fixed-wing and Quadrotor UAVs Testbeds (Dr. Zhang)
- 3.09:40 10:15: Iterative Design Towards Improved Fault Tolerance: A Framework for Improved SUAS Airworthiness (Dr. Chen)
 - 10:15 10:30 Coffee Break/Networking
- 4. 10:30 11:05 Sliding Mode Schemes for Fault Detection and Fault Tolerant Control (Dr. Edwards)
- 5. <u>11:05 11:40</u> H∞ Detection, Isolation and Tolerant Control: A Tutorial on Aerospace Applications (Dr. Marcos)
- 6. 11:40 12:15 Reconfigurable Flight Fault Tolerant Control for Nonlinear Unmanned Aerial Vehicle (Dr. Patton)
 - 12:15 13:30 Lunch

Outline of the Tutorial

- 7. 13:30 14:05 Nonlinear Fault Diagnosis and Fault Tolerant Control Schemes for Aerospace Applications (Dr. Castaldi and Dr. Simani)
- 8. 14:05 14:40 Design of Fault-tolerant Control Methods Based on Reliability (Dr. Theilliol & Dr. Zhang)
- 9. <u>14:40 15:15</u> Multiple UAS Operations: Toward Verifiable Autonomy (Dr. Tsourdos)
 - 15:15 15:30 Coffee Break/Networking
- 10. 15:30 16:05 Fault Diagnosis and Tolerant Control of Aerospace Systems using LPV Techniques (Dr. Puig)
- 11. 16:05 16:40 Fault Diagnosis and Fault Tolerant Control for Civil Aircraft: Industrial State-of-Practice for Flight Control Systems (Dr. Goupil)
 - 16:40 17:00 Summary, Discussion, and Feedback (All)